

**Listing of claims:**

Claim 1 (Currently amended): A method of handling a load at a high desired load handling position comprising the steps of:

a) using a mobile loading machine of the kind having a loading arm connected at one end to a body of the machine, the arm arranged for raising and lowering movement at least about a generally horizontal axis between a lower traveling position, and a higher load handling position, and the arm having an outermost end having a loading implement for carrying the load;

b) manoeuvring the machine with the arm in the lower traveling position generally below the load handling position, and then one of:

c) directing a signal from a vertically fixed position on the body upwardly towards the load handling position in a plane in which a reference point of the loading implement is movable as the arm is raised about the generally horizontal axis[[], or

d) directing a signal downwardly from a vertically fixed position disposed at or adjacent the load handling position to a vertically fixed receiver operatively coupled to the body, the signal directed in a plane in which a reference point of the loading implement would be moveable if the arm is raised about the generally horizontal axis with the machine in a correct lateral position,]]

to ascertain whether the machine is correctly laterally positioned so that if the arm is lifted, the loading implement is positionable at the load handling position, manoeuvring the machine as necessary until the machine is correctly laterally positioned and then raising the loading arm to raise the loading implement towards the load handling position.

Claim 2 (Original): A method according to claim 1 wherein the signal is directed from the machine upwardly towards the load handling position, and the signal is light which is directed as a fan of light in the plane of movement of the reference point.

Claim 3 (Original): A method according to claim 1 wherein the light is high intensity light such as collimated laser light.

Claim 4 (Original): A method according to claim 1 wherein the reference point of the loading implement is a laterally central position of the loading implement, which lies generally along an elongate axis of the loading arm.

Claim 5 (Original): A method according to claim 2 wherein the light is directed upwardly towards the load handling position from an illuminating device carried on one of the loading arm and the body of the machine to direct the light in the plane.

Claim 6 (Canceled)

Claim 7 (Previously presented): A method according to claims 1 or 4 wherein the arm includes a plurality of relatively telescopic sections, the method including extending the arm to move the loading implement axially of the arm towards the load handling position.

Claims 8-17 (Canceled)